

# **The Role of Robotic Outposts in Establishing a Permanent Presence in Space**

**Third Annual Carl Sagan Memorial Lecture  
American Astronautical Society**

**November 16, 1999**

**E. C. Stone, Director**

**Jet Propulsion Laboratory  
California Institute of Technology**

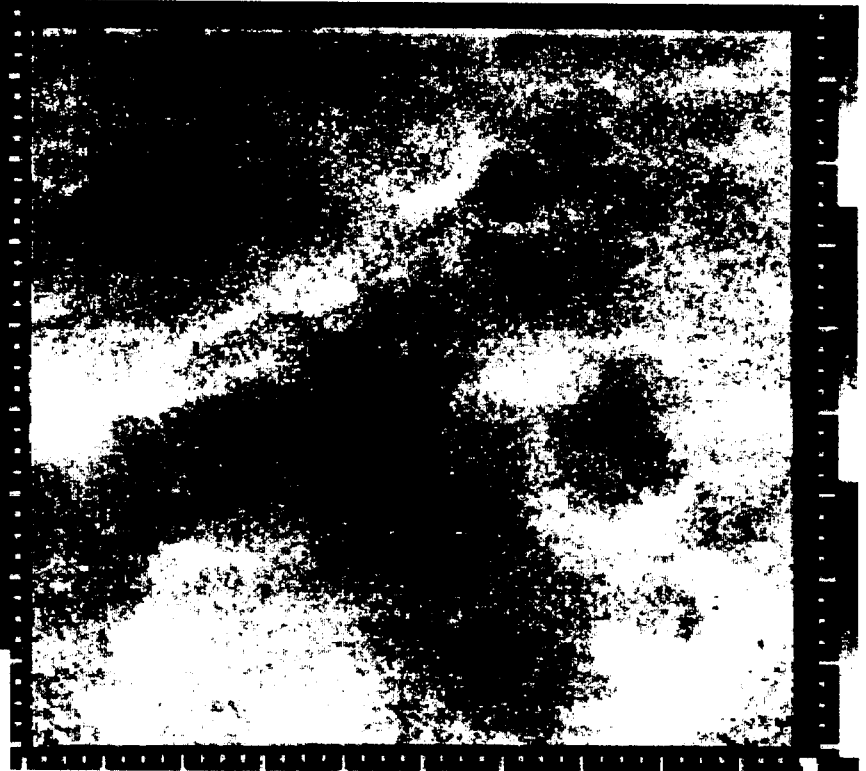
# **Topics**

- The Eras of Space Exploration
- The Role of Robotic Outposts
- Establishing and Evolving a Permanent Presence
- Technologies
- Paving the Way for Future Exploration

# The First Era: Getting There



Mariner 4



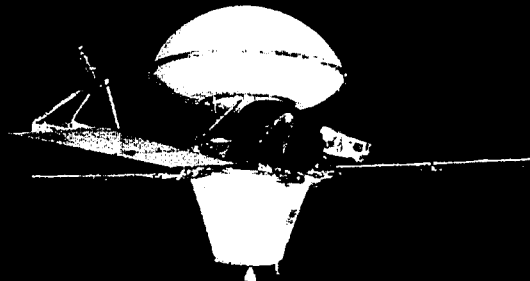
Mariner 4 View of Crater Rims -  
Southern Highlands of Mars

# The Second Era: Finding Out What's There

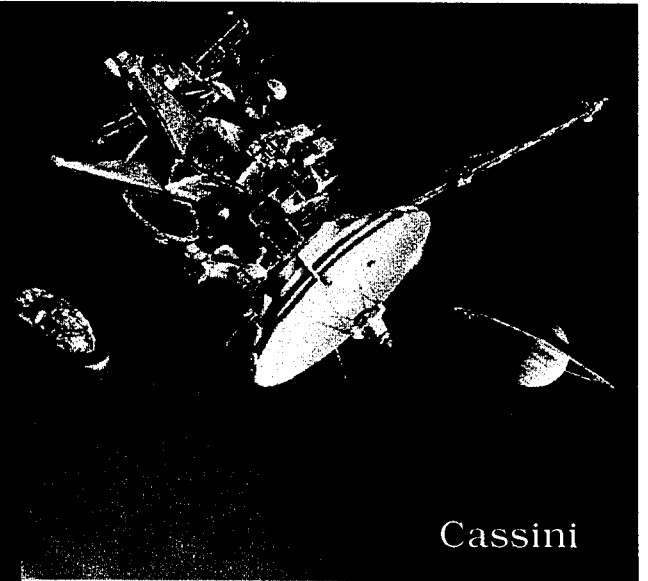
Magellan



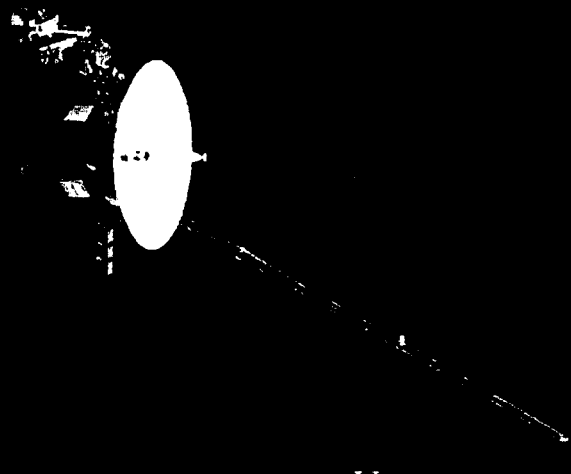
Viking



Cassini



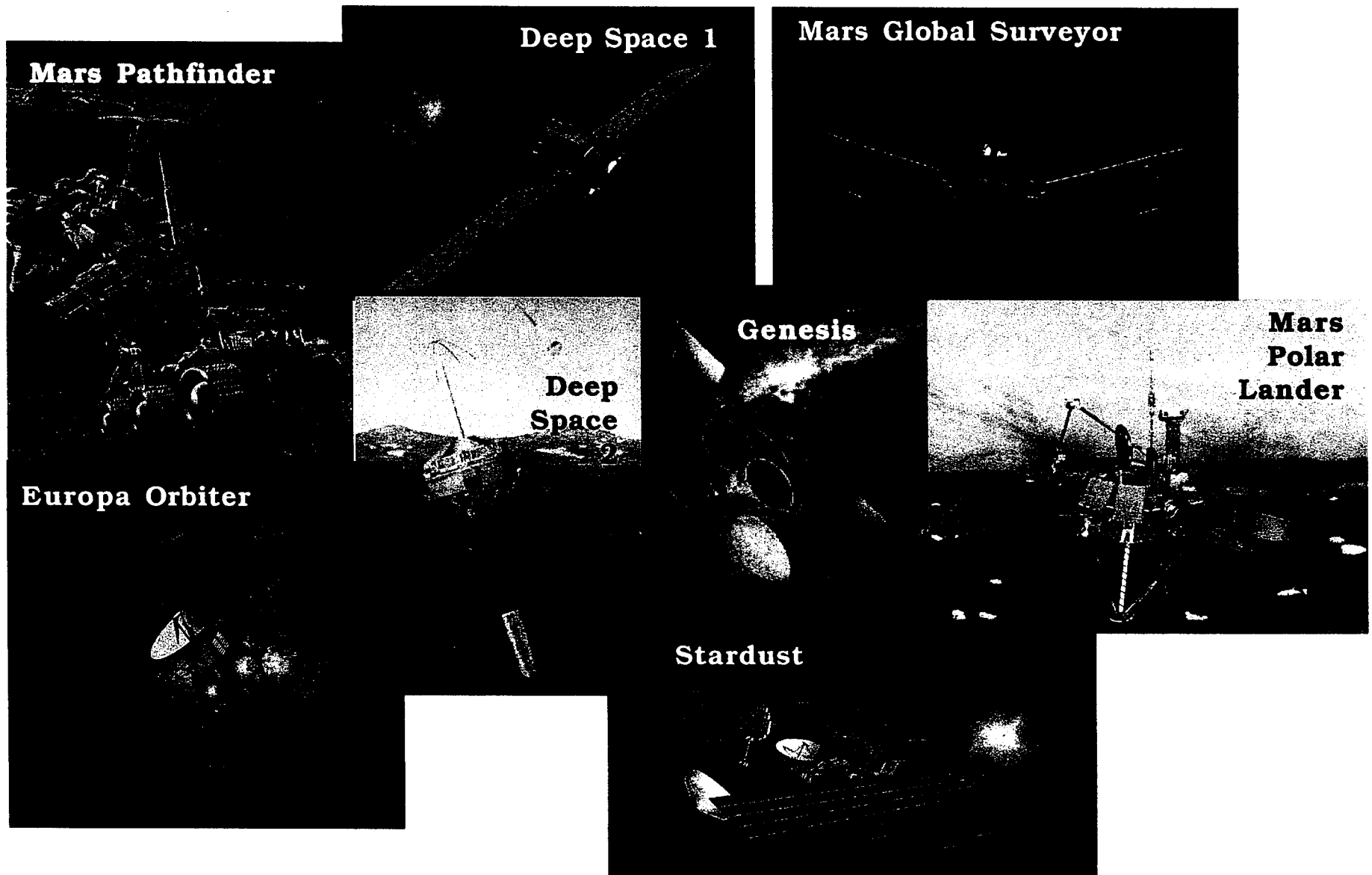
Voyager



Galileo



# The Third Era: Going Often, Landing, and Bringing Samples Back



# Second and Third Era Characteristics

## Second Era

Individual Projects

Large, Comprehensive Observatories

Global Scale Exploration

Remote Sensing

## Third Era

Programs of Linked Projects

Small, Focused Systems

Local Scale Exploration

*In Situ* Sensing

# **The Fourth Era: Permanent Presence**



# Third and Fourth Era Characteristics

## Third Era

Episodic Surface Activities

Localized Mobility

Limited Power

Limited Communications

Bring Resources from Earth

## Fourth Era

Continuous, Cooperative Operation

Long Range Mobility

Sustained, Substantial Power

Continuous, High-bandwidth Network Communication

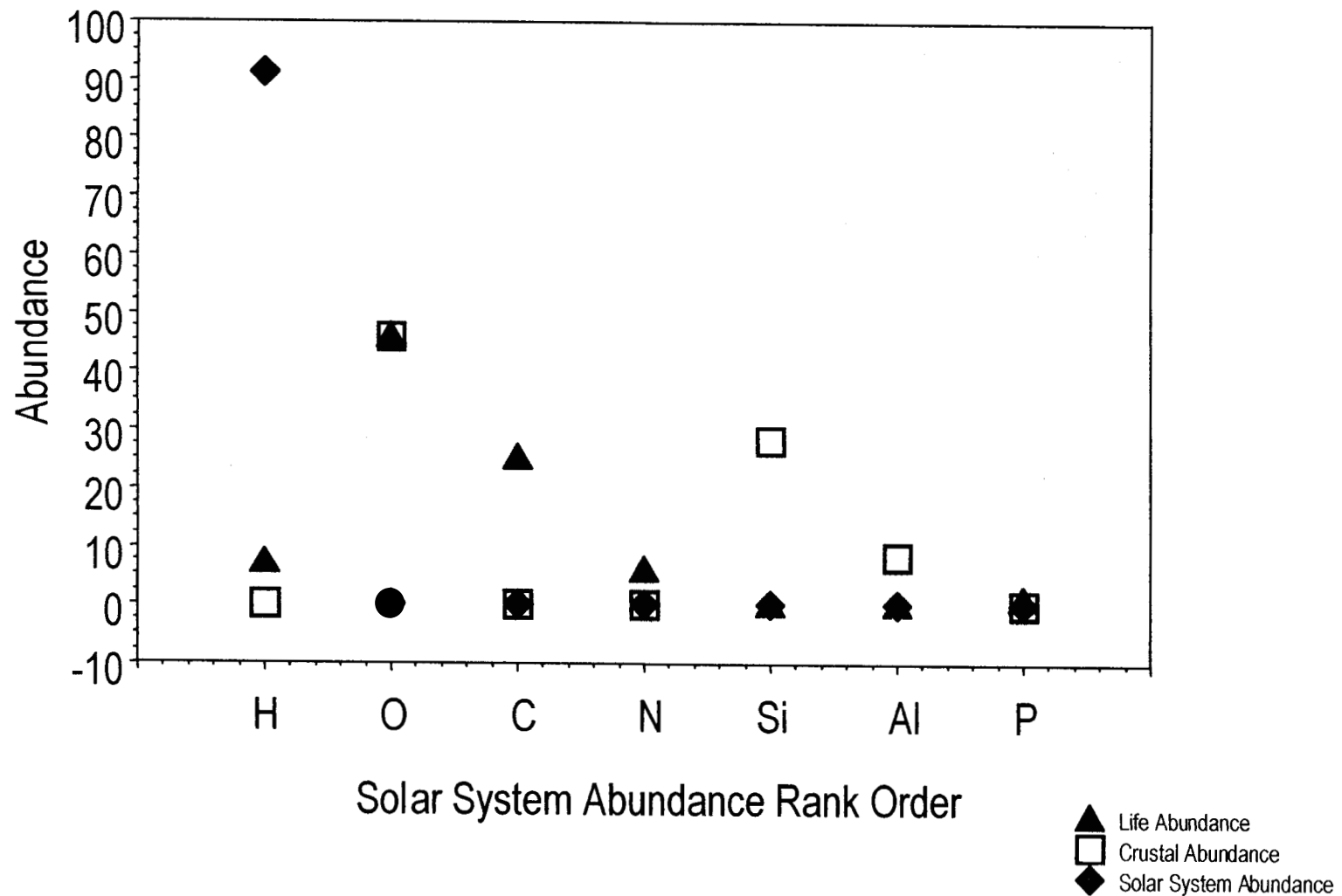
Use *In Situ* Resources



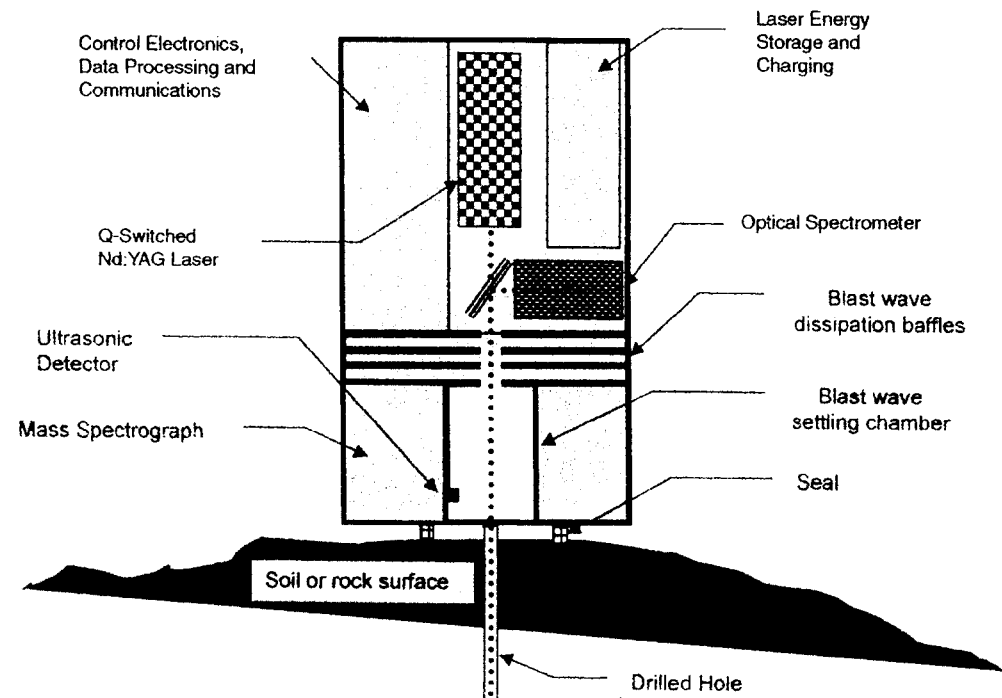
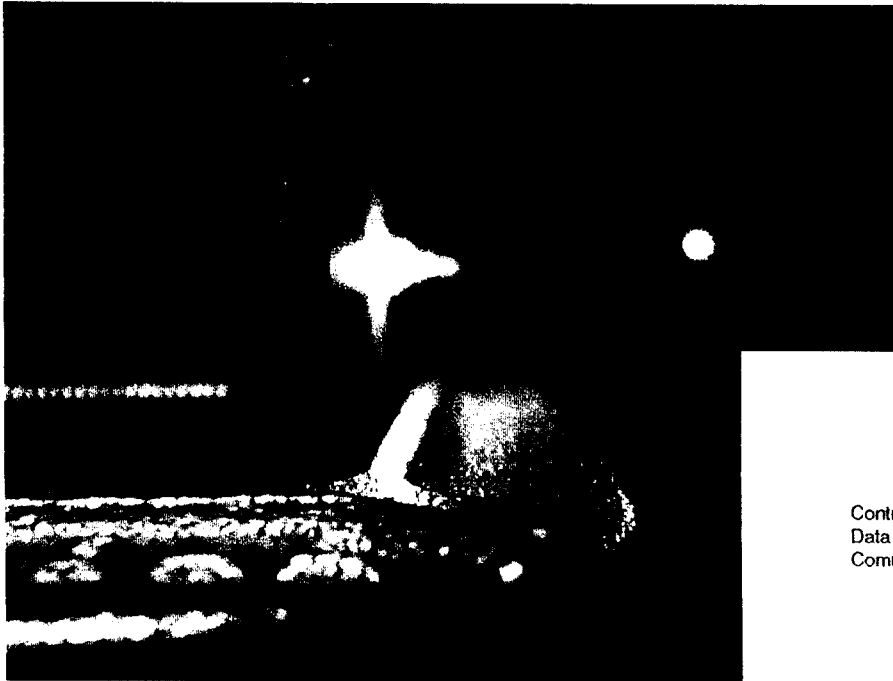
# **The Role of Robotic Outposts**

- Advanced Scientific Activities
  - Search for Extant Life
  - Planetary History and Evolution
- Public Engagement
- Support Human Exploration
  - Understanding the Environment and Resources
  - Providing Infrastructure and Technology

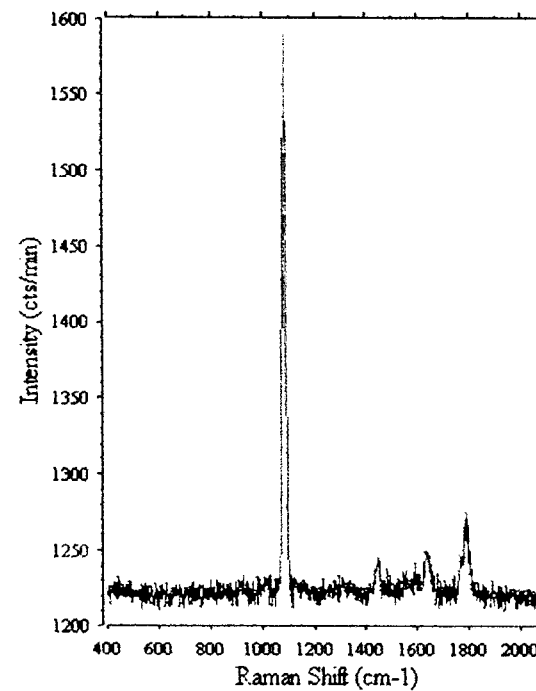
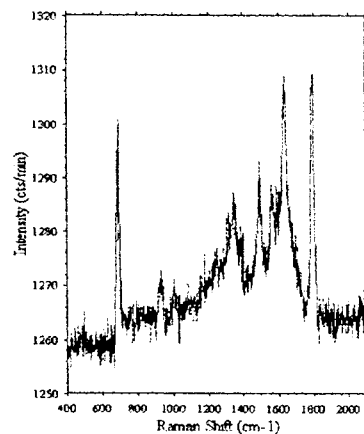
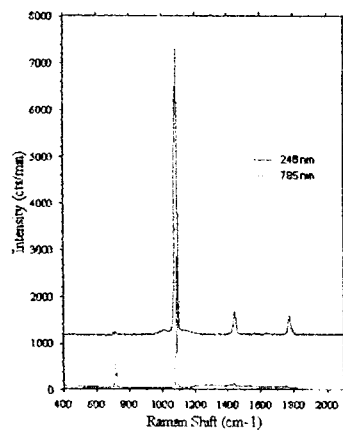
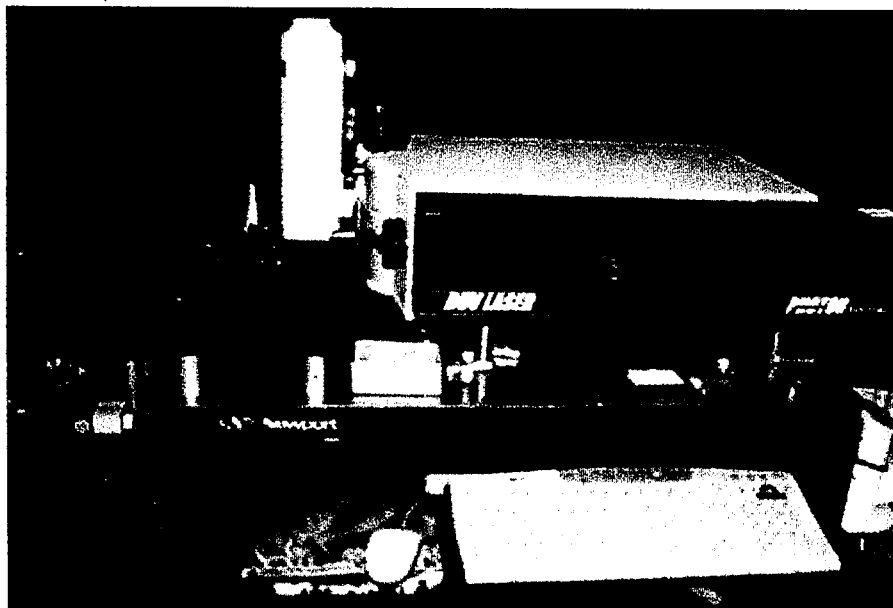
# Elemental Abundance in Living Organisms and Earth's Crust



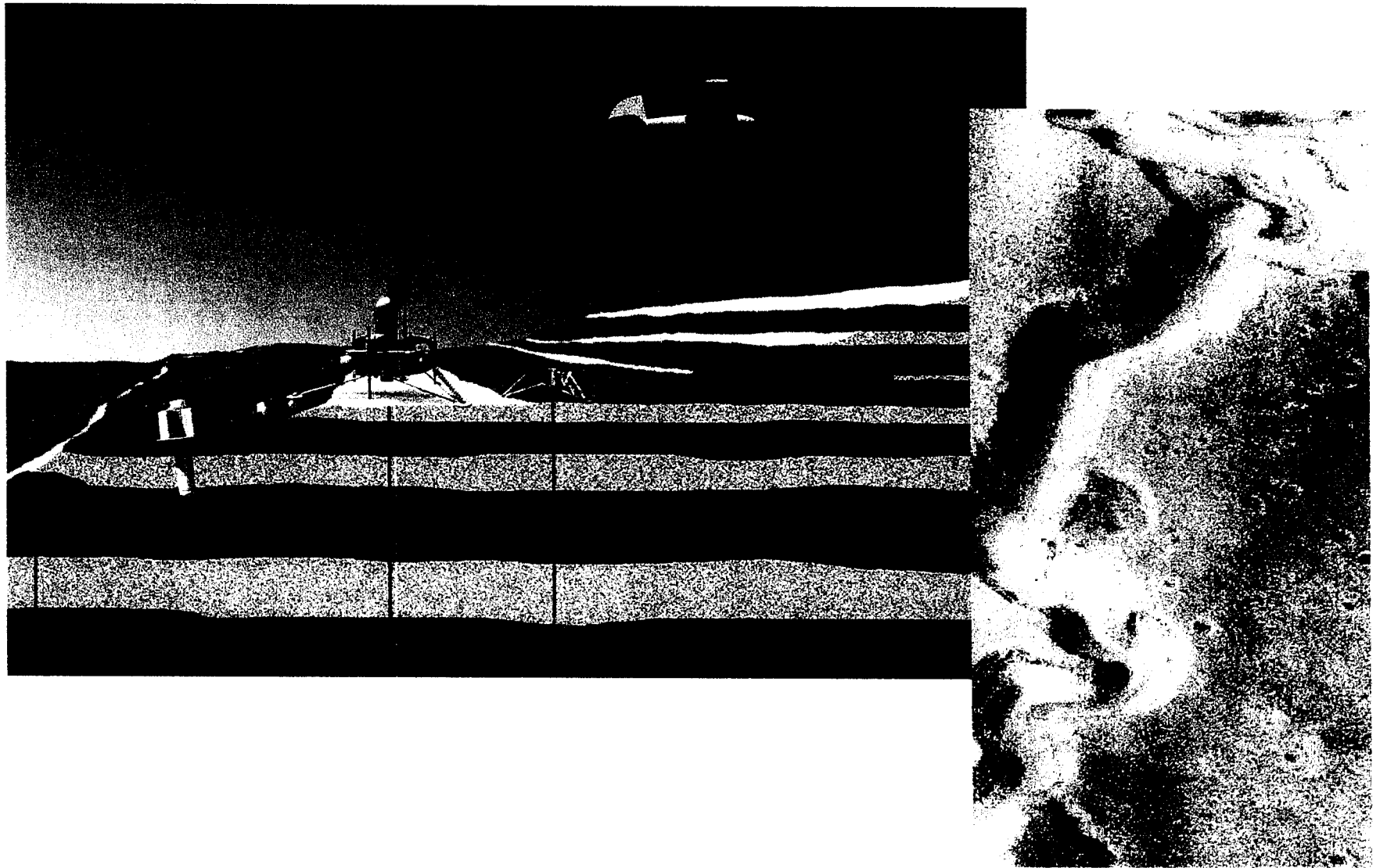
# Enhanced Science: Laser Ablation and Spectroscopic Analysis



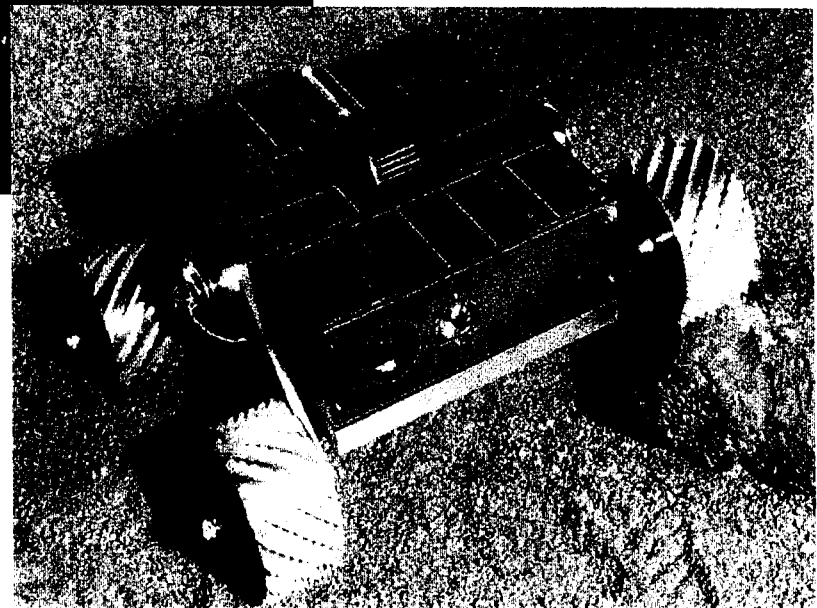
# Enhanced Science: Ultraviolet Raman Spectroscopy



# Planetary History and Evolution



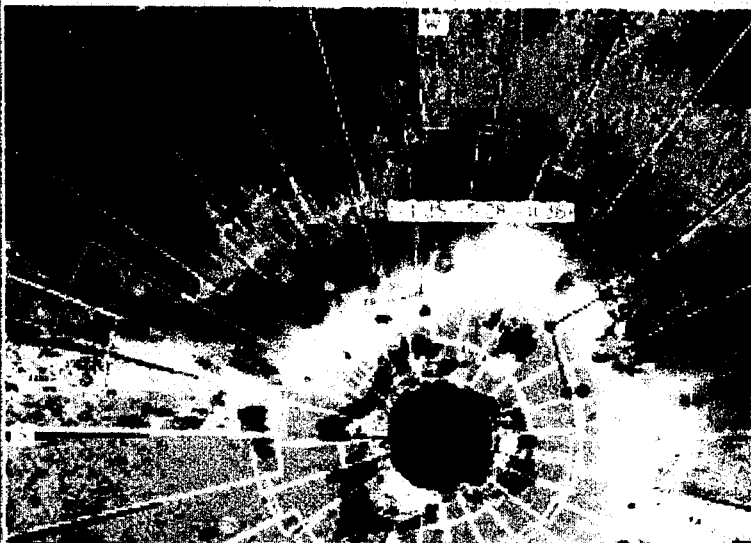
# Public Engagement



File Edit Action View Sequence Window



Date: [ ] Cycle: 1 Map: Elevation

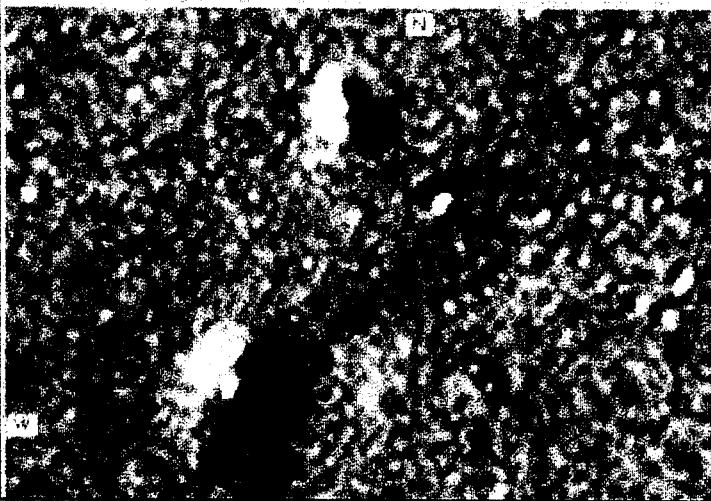


Descent View

File Edit Action

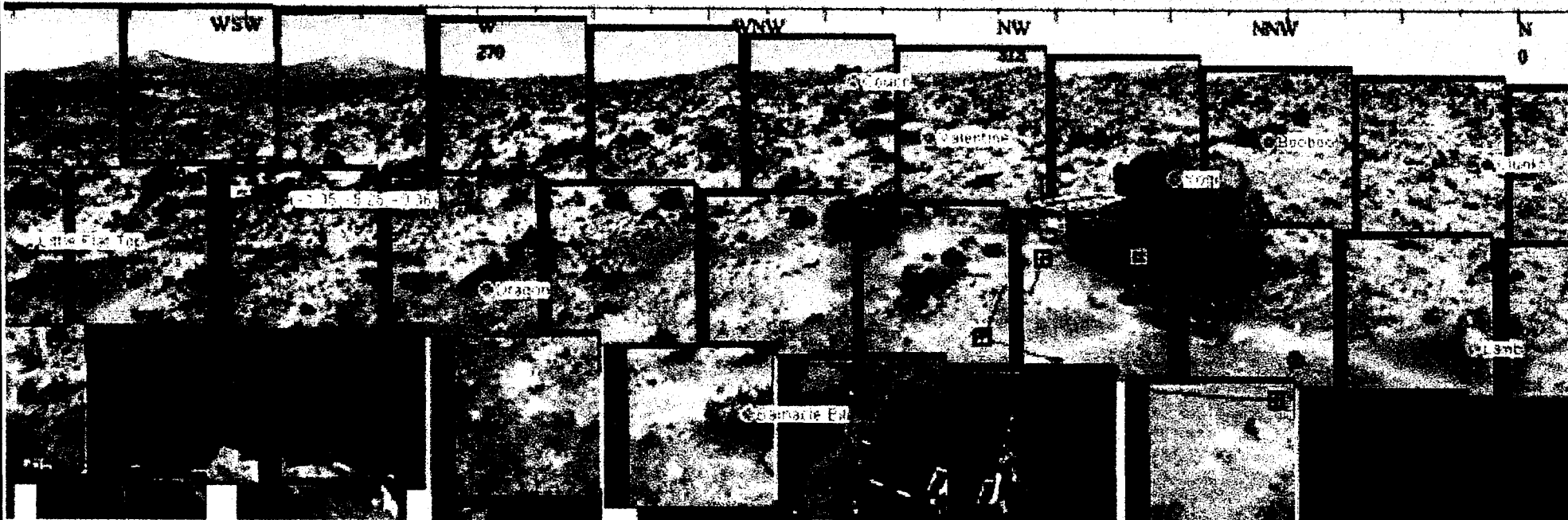


Altitude: 9999 Image: Color



Mosaic View

File Edit Action Center Scale View

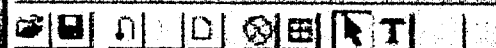


Window Help



Wedge View

File Edit Action



Penetration

27.56 Unsigned Java Applet Window

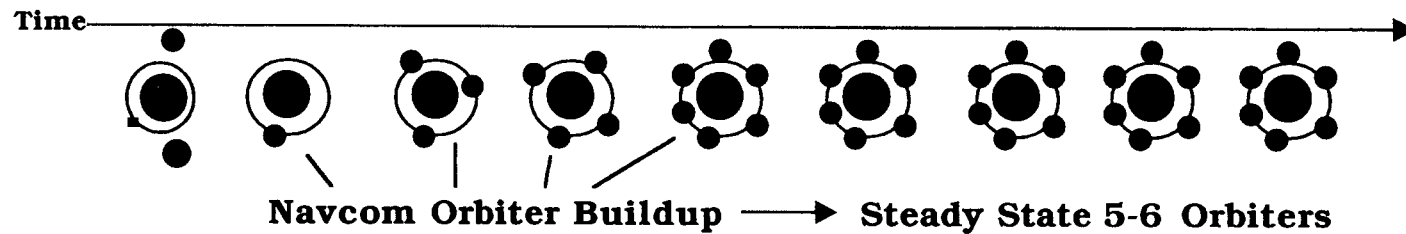
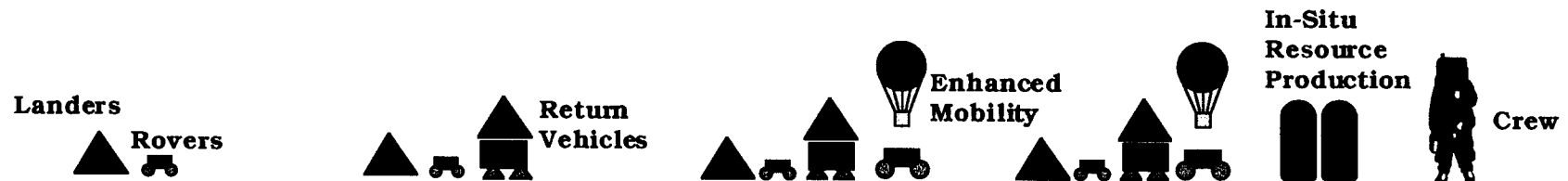
# Support Human Exploration

*Robotic Exploration*

*Sample Return*

*In-Situ Science*

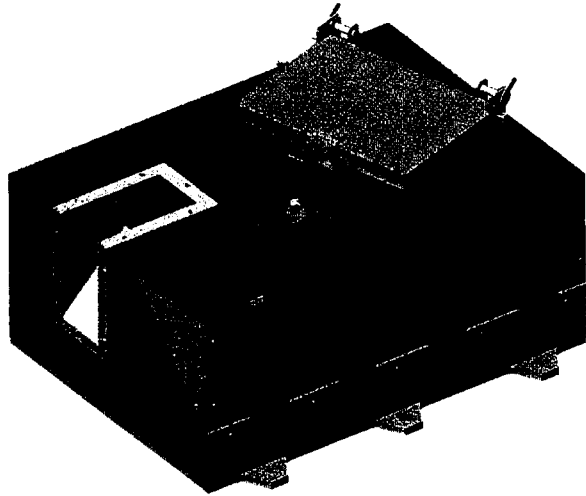
*Support for Human Presence*



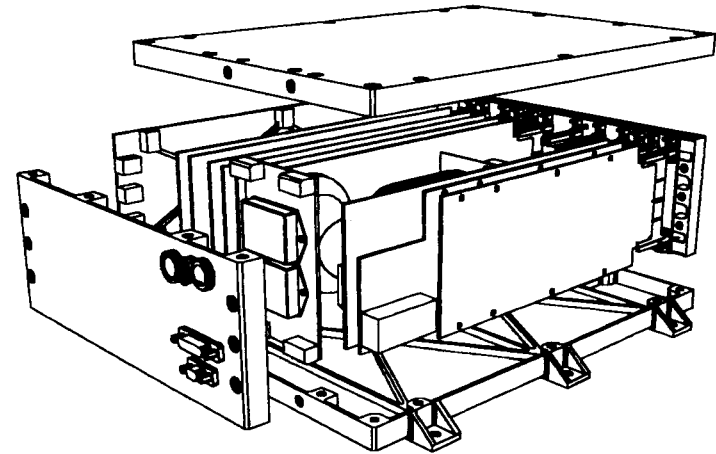


# Understanding the Environment and Resources: Mars '01 Lander

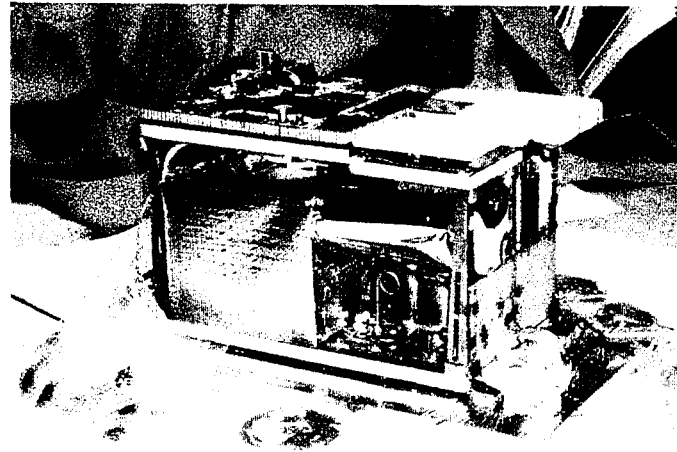
**Mars Environmental Compatibility Assessment (MECA)**



**Martian Radiation Environment Experiment (MARIE)**

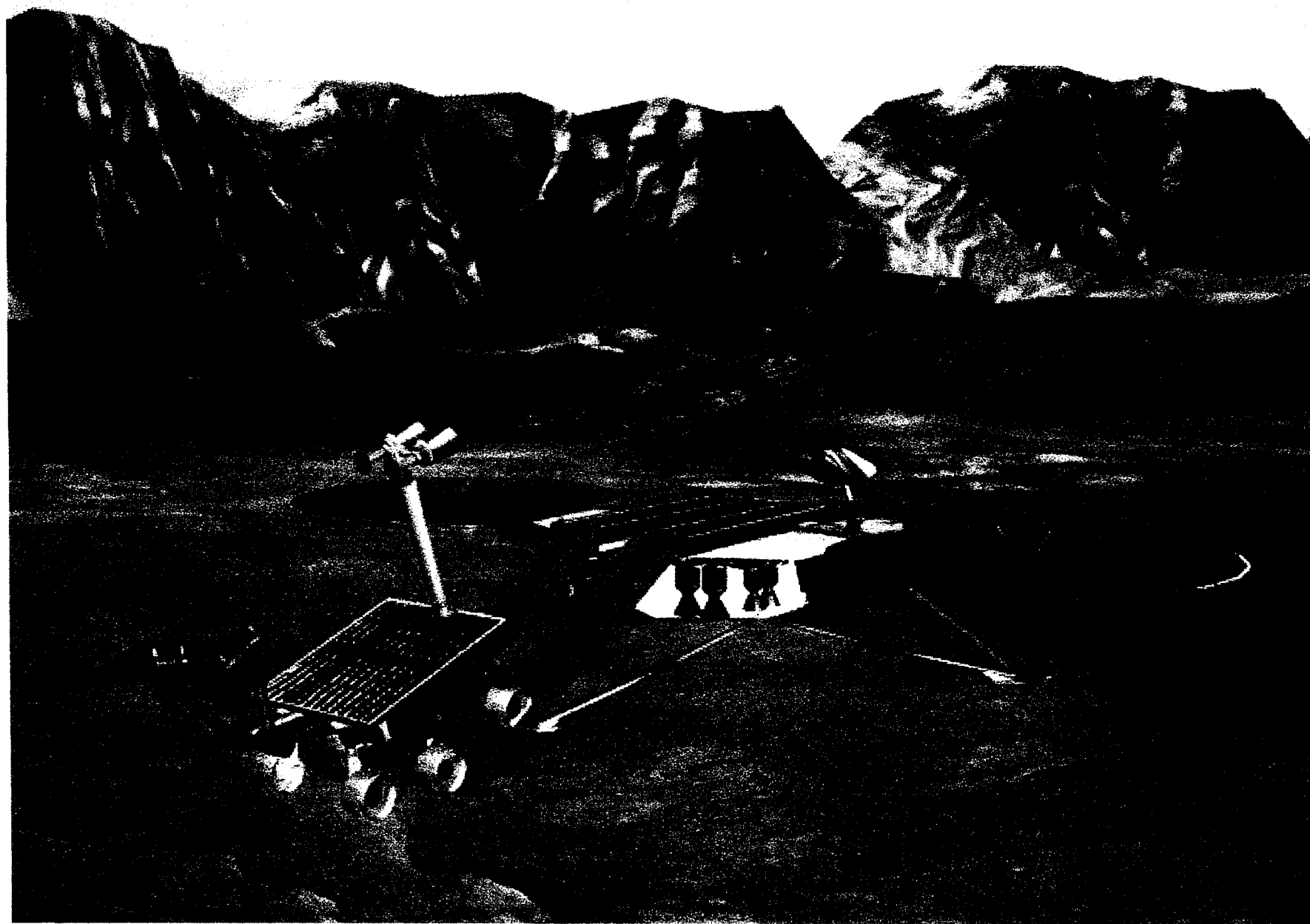


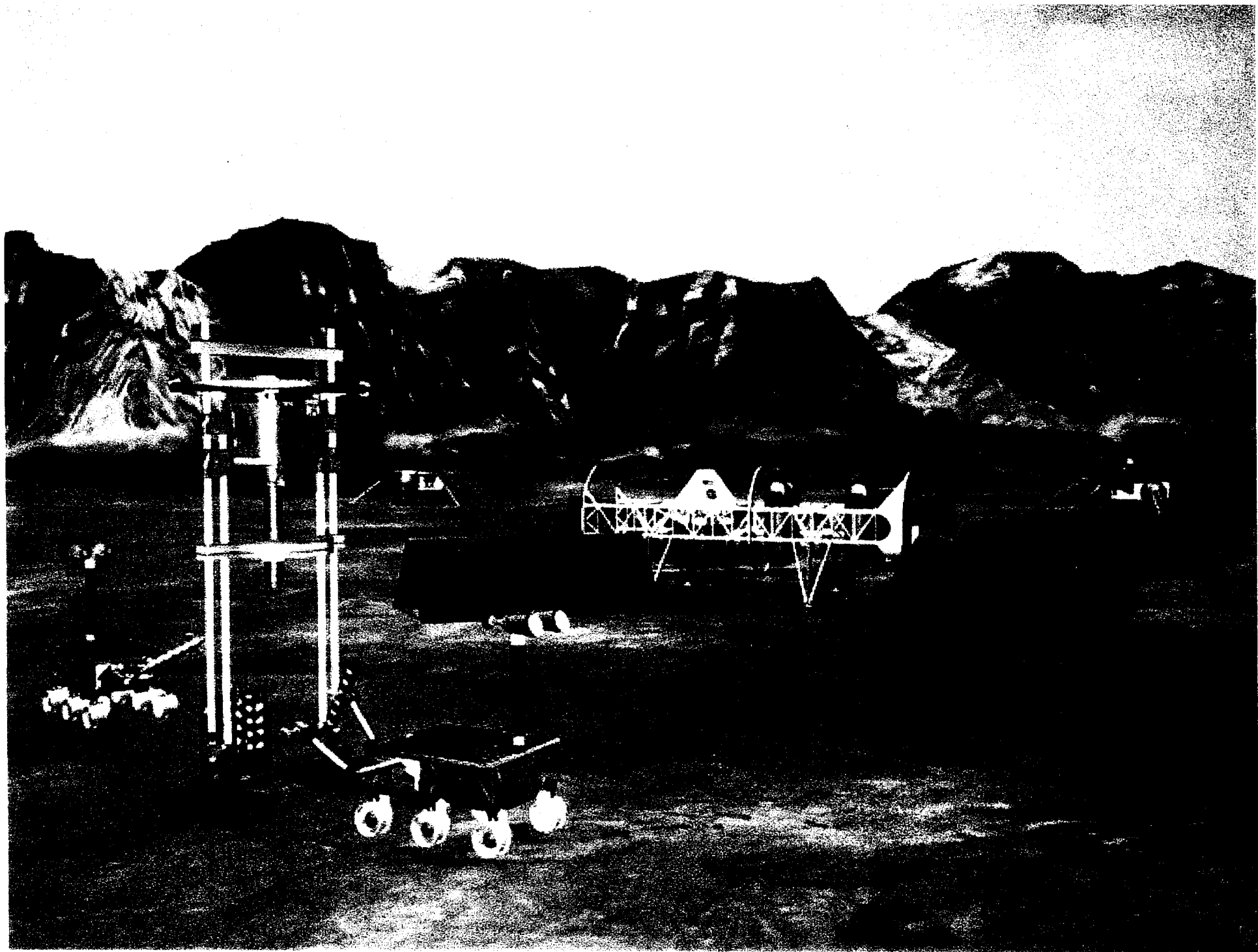
**Mars ISPP Precursor (MIP)**

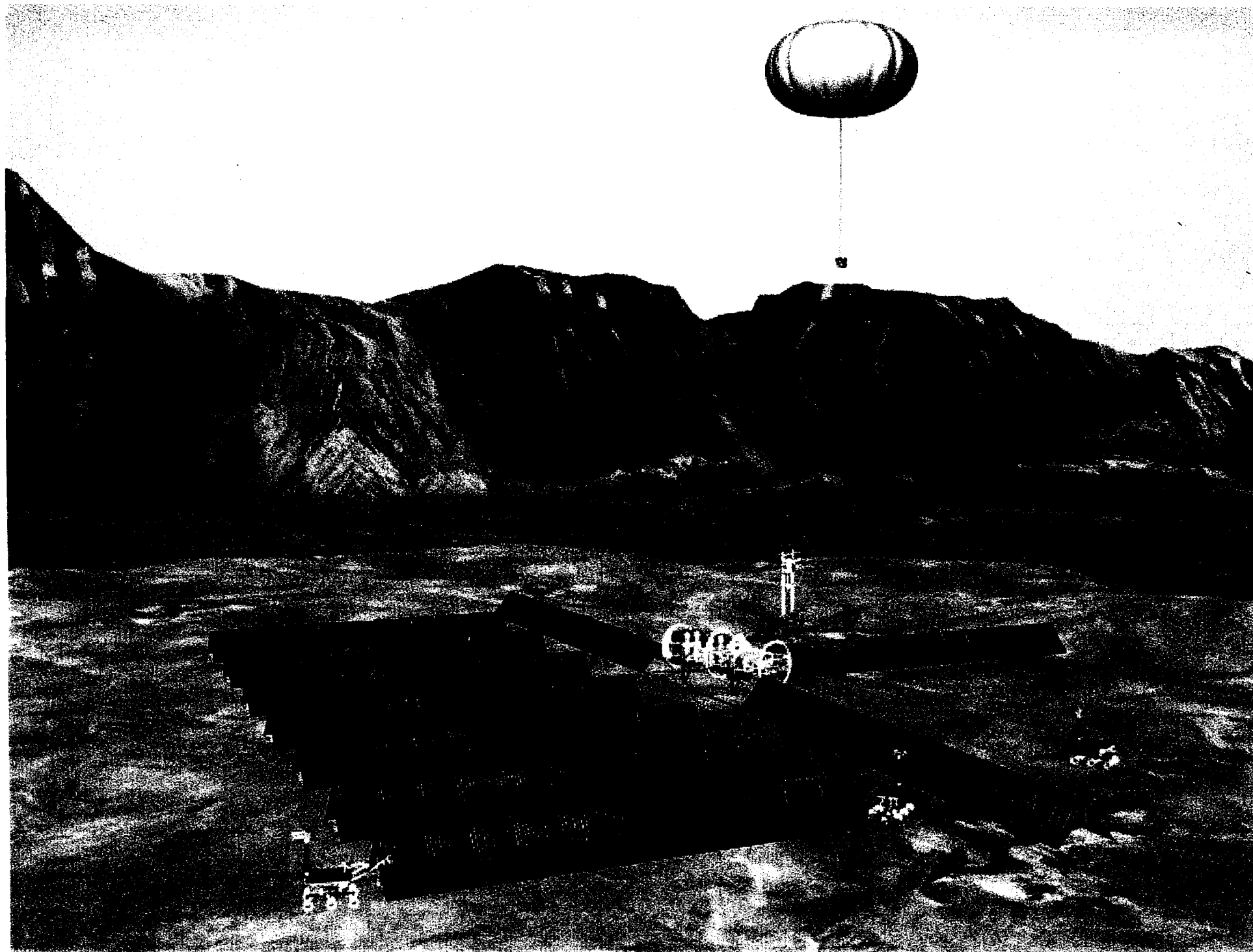


# **Establishing and Evolving a Permanent Presence**

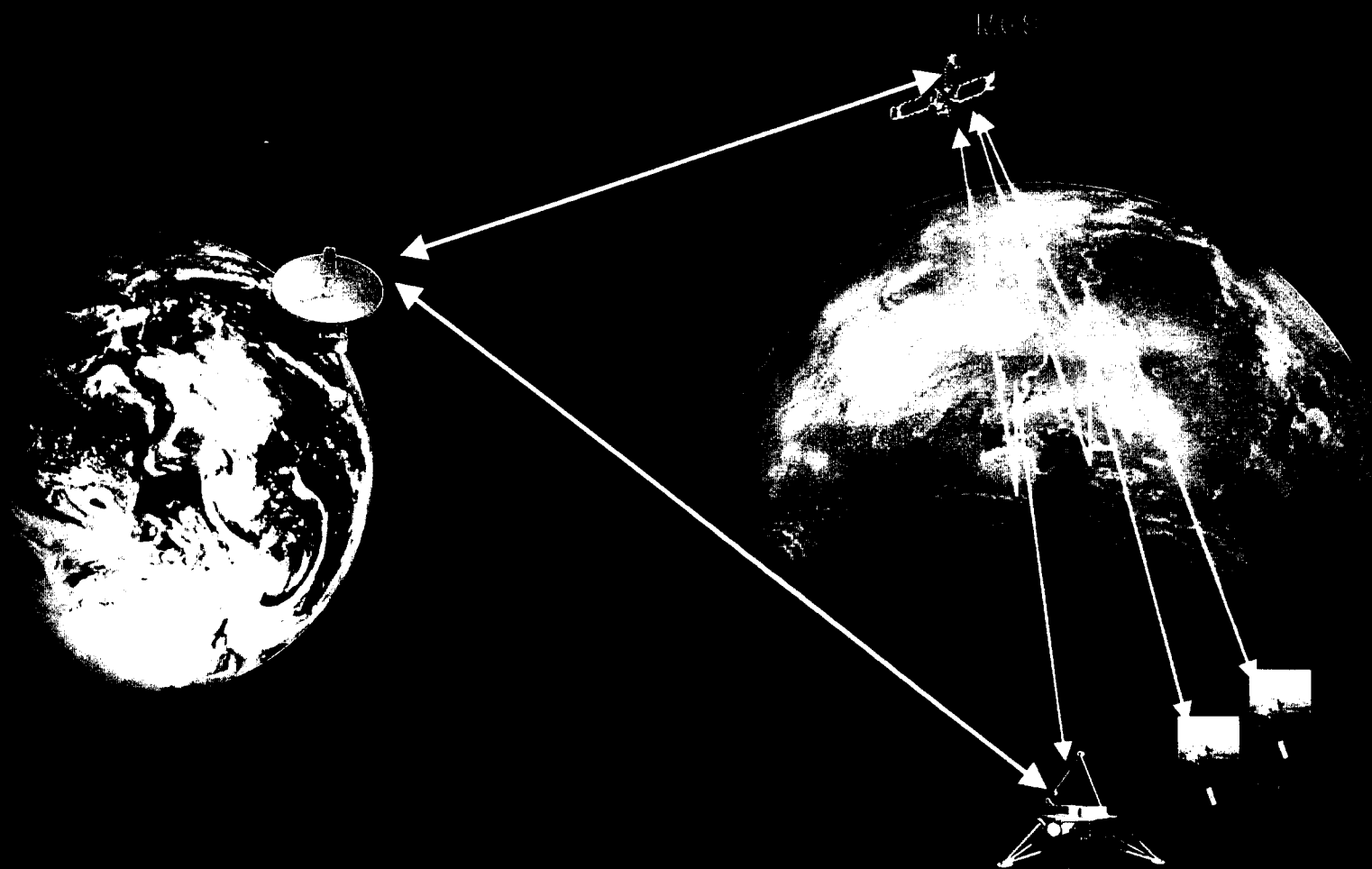
- Choose 1-2 locations
- Develop incrementally
  - On the surface: power and resources node
  - In orbit: communication and navigation nodes

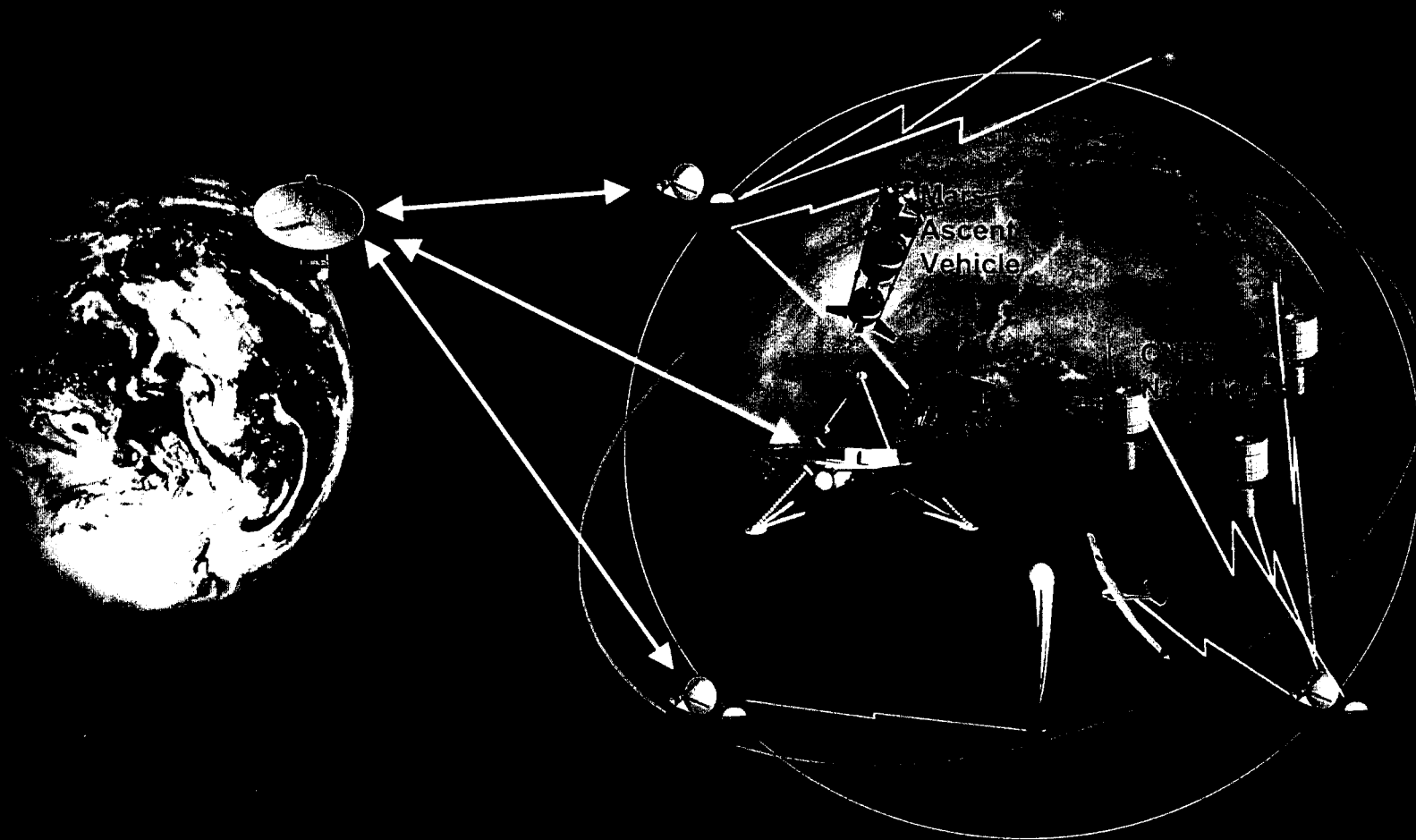


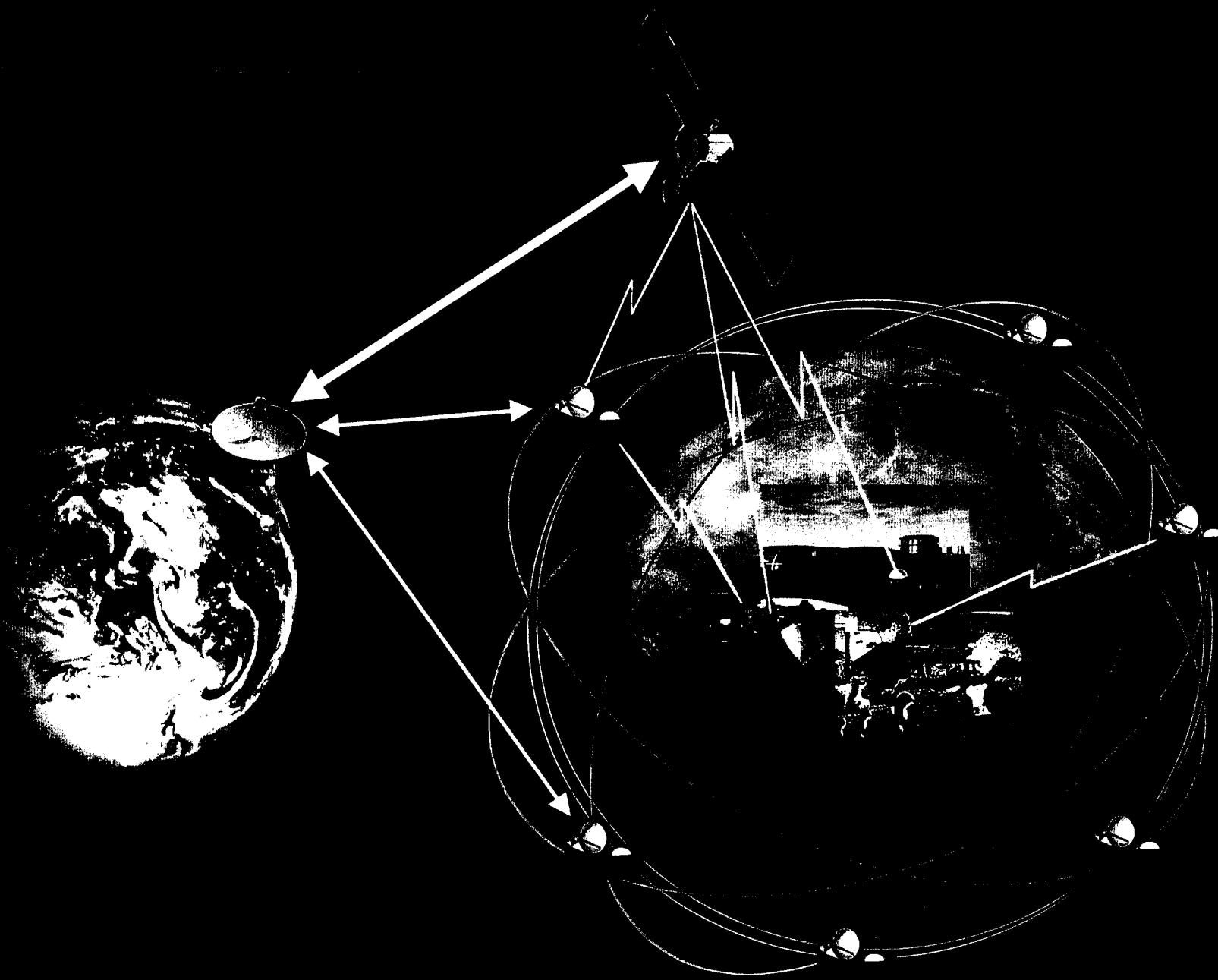




# Mars Infrastructure Tech



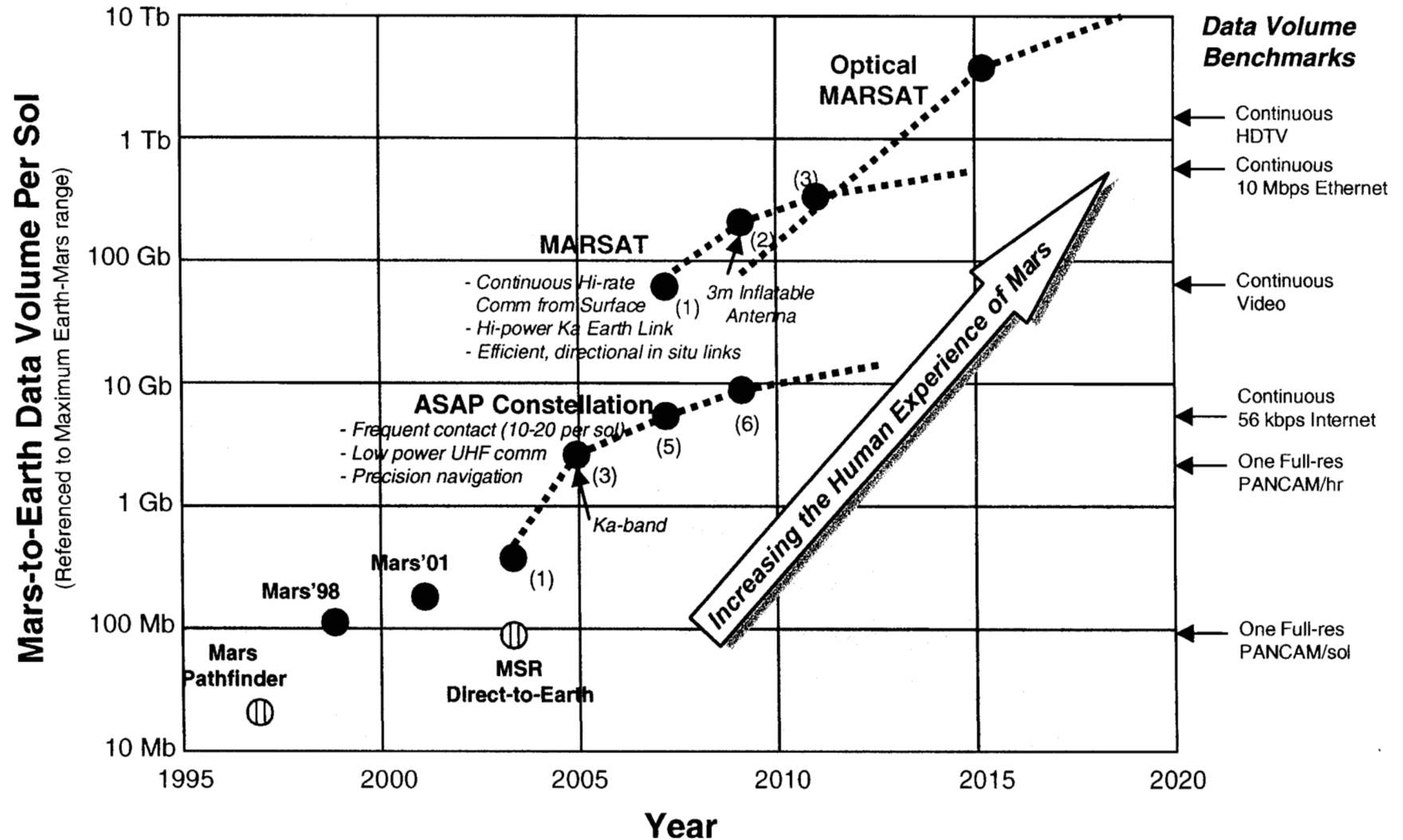






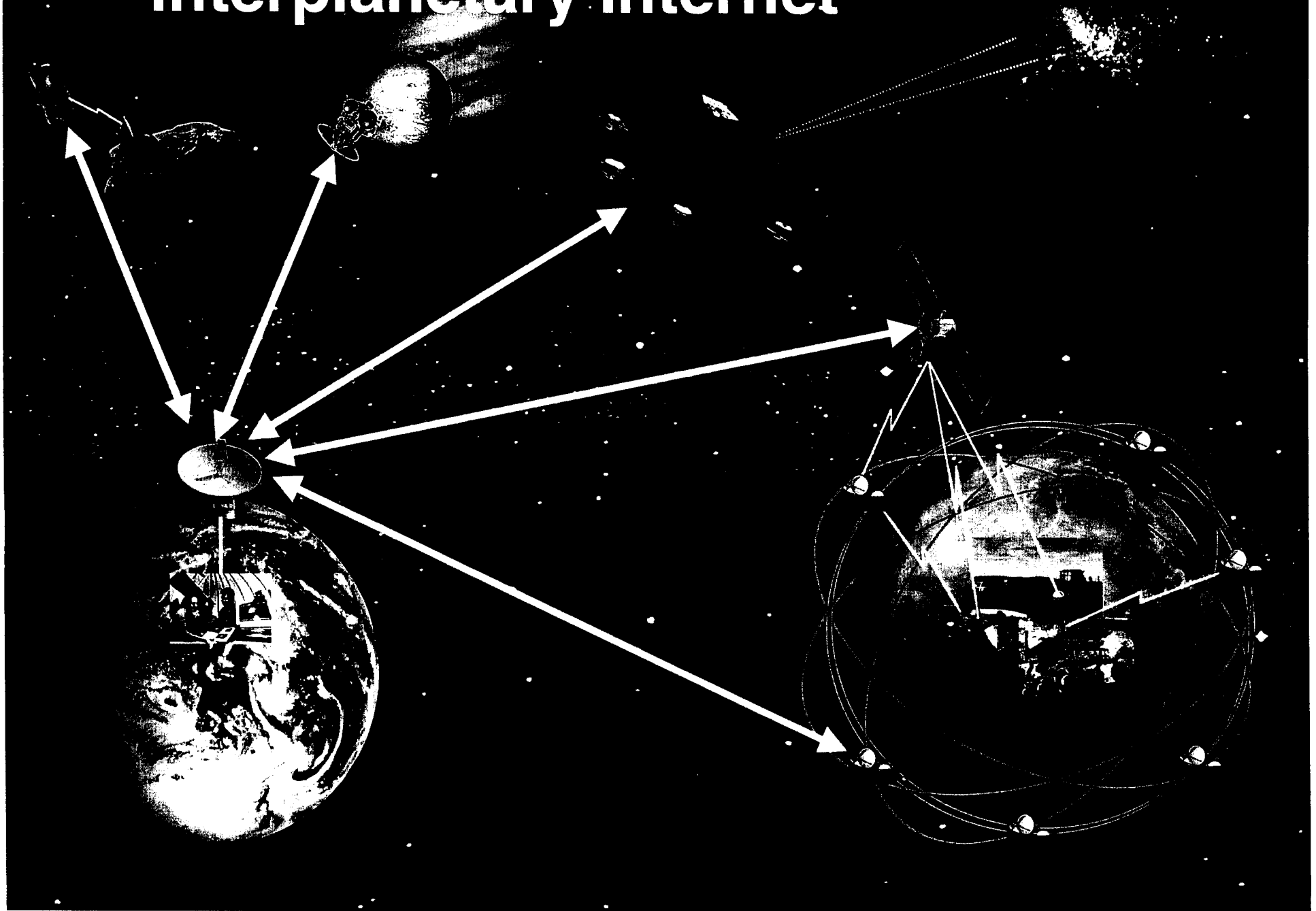
# Mars Network Evolution

- Aggressive technology infusion will allow orders-of-magnitude growth in communications capability, enabling radical increases in the fidelity of Mars virtual presence





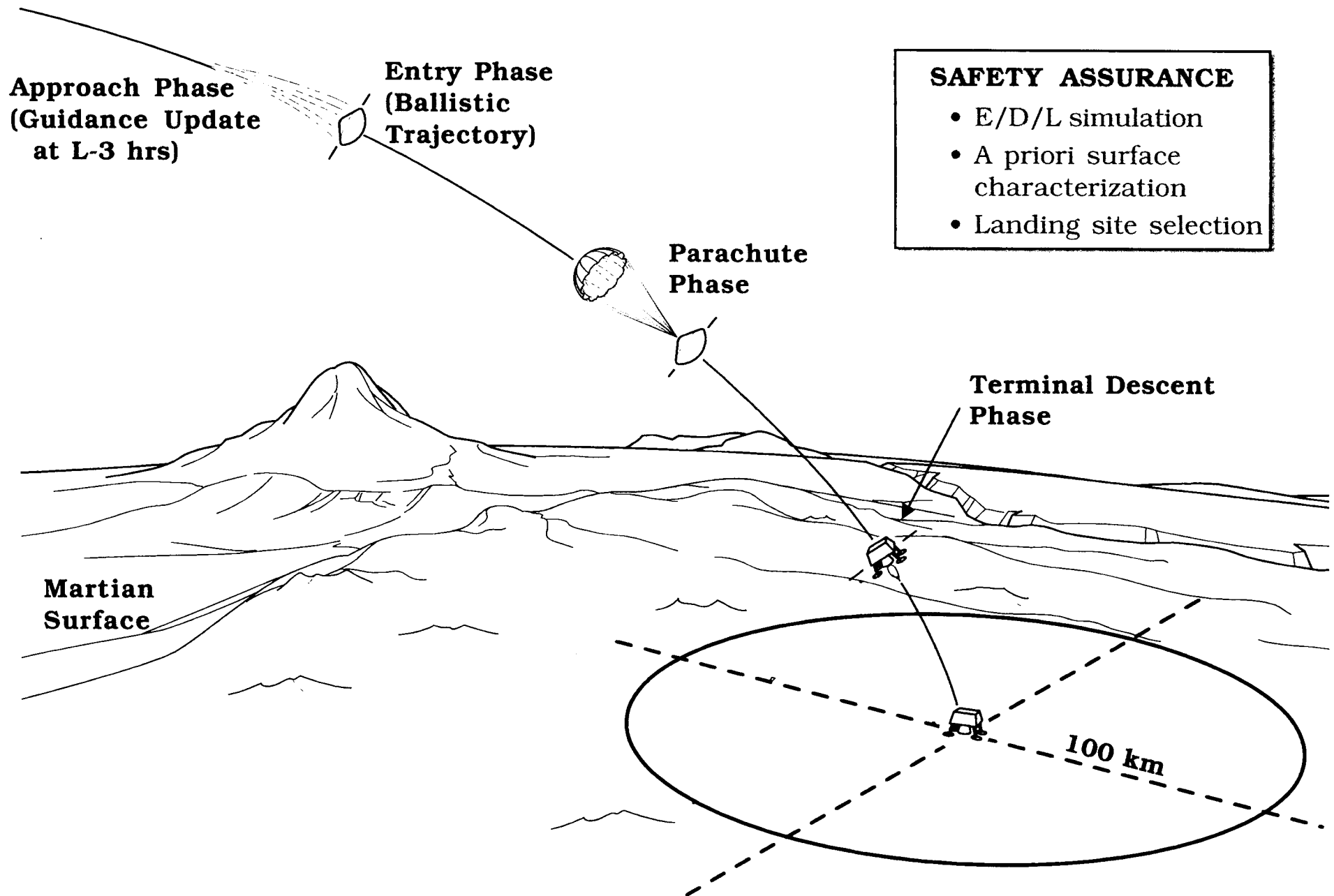
# Interplanetary Internet



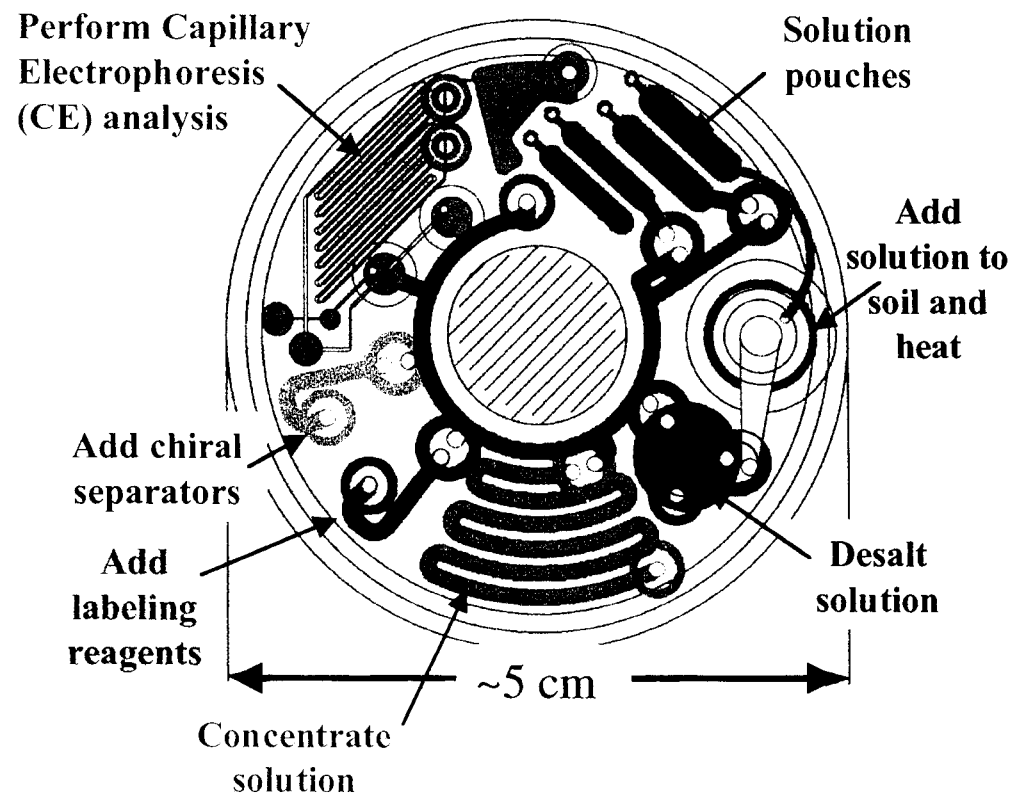
## **Key Technologies**

- High-bandwidth Communication
  - Precision Landing
  - “Biochemistry Lab in a Teacup”
  - Mobility
  - *In Situ* Resource Utilization
-

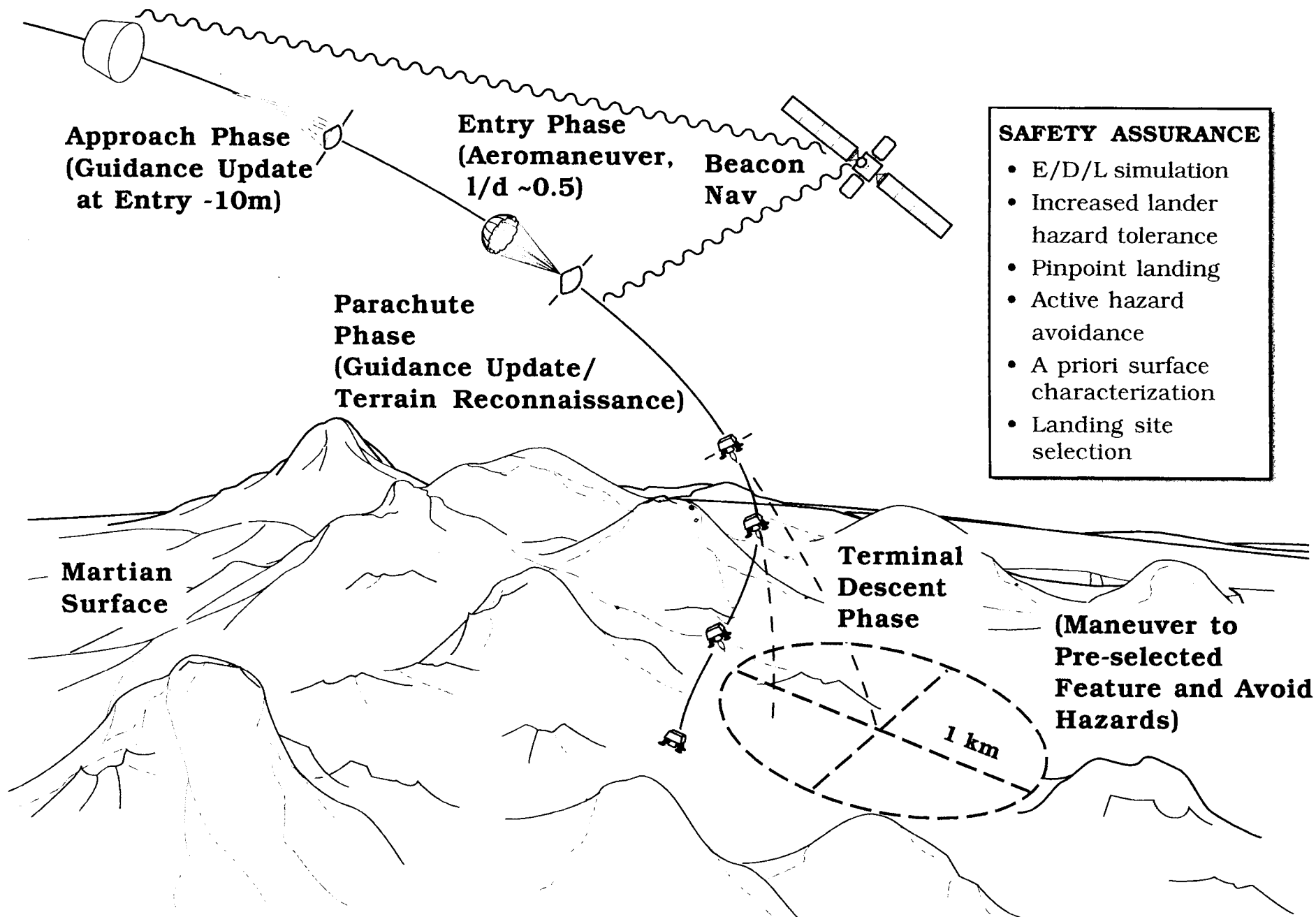
# Precision Landing: Mars '98



# “Biochemistry Lab in a Teacup”



# Precision Landing: Mars '07/'09 and Beyond

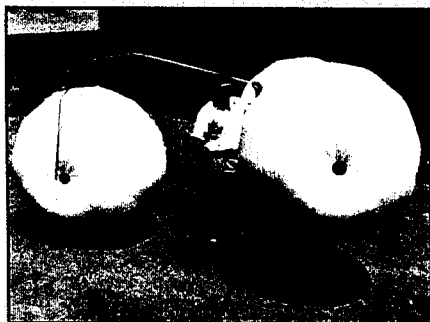




# Surface Mobility Roadmap

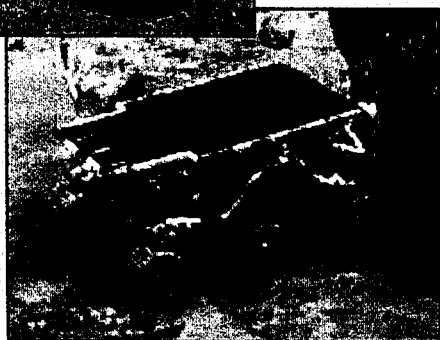
*Unlocking the secrets of the Red Planet*

## Innovative Mobility Systems

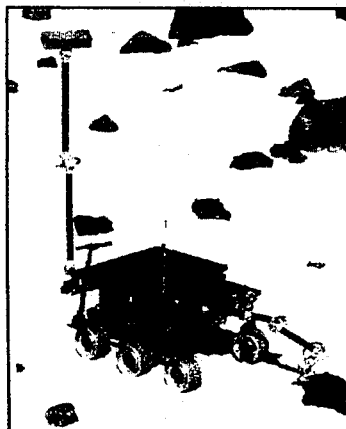


*Inflatable  
Rover*

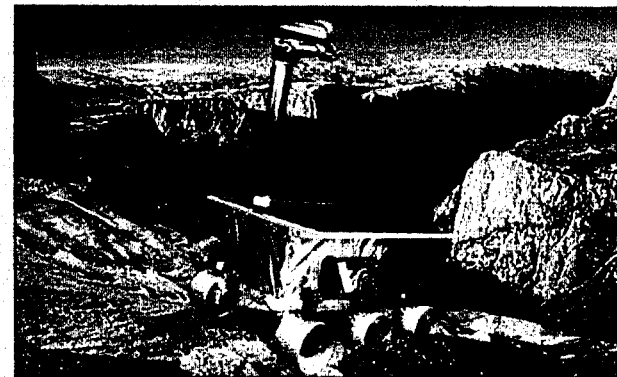
*Sojourner  
on Mars*



## Mobile Sample Acquisition System



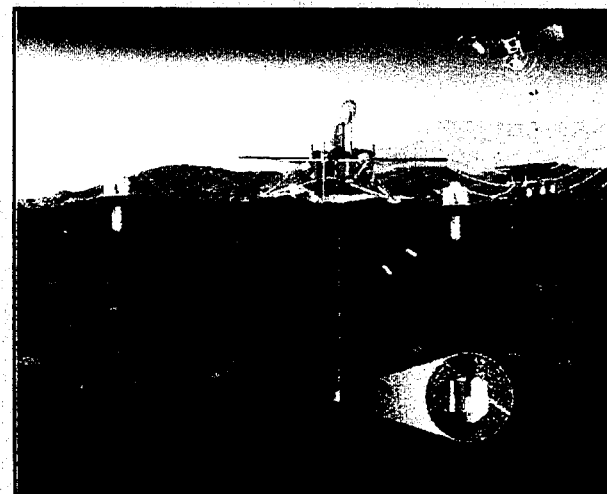
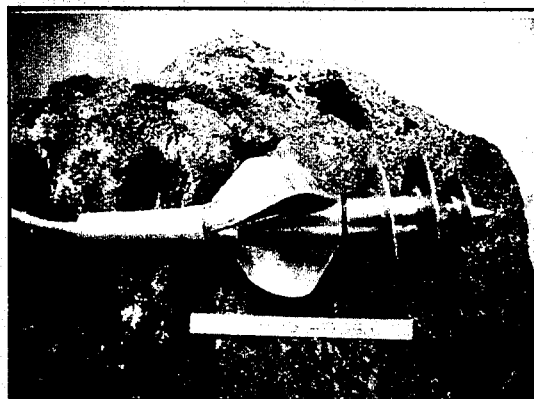
## Autonomous Robotic Exploration





# Subsurface Mobility Roadmap

*Access to the subsurface of Mars with innovative robotic techniques*

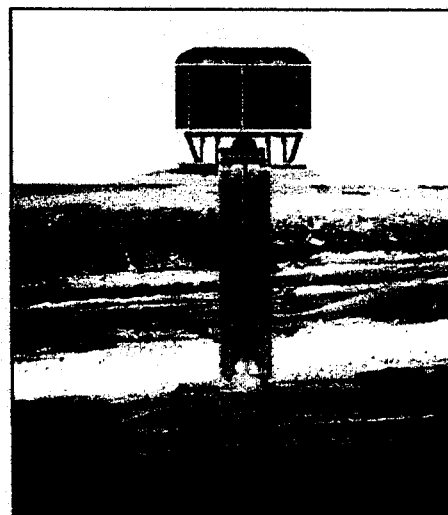
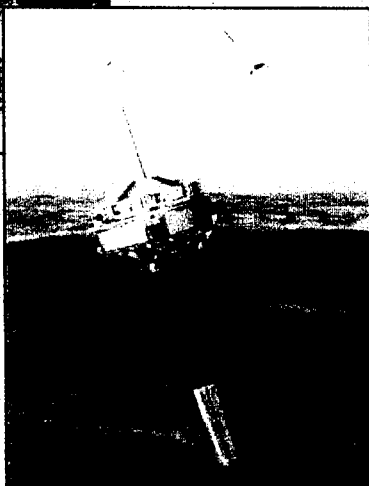


**Deep Drilling Systems**

**Subsurface robots for penetrating  
sediments and ice deposits**



**Surficial and  
shallow  
sampling of  
rocks and soils**





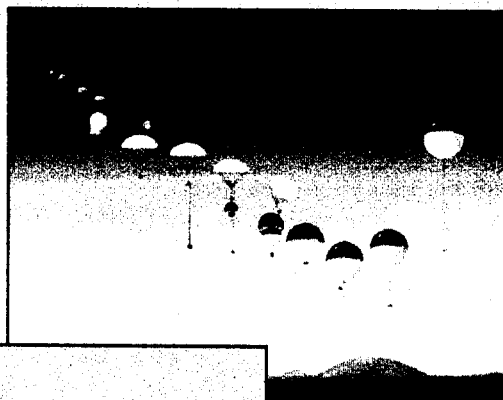


# Aerial Platforms Roadmap

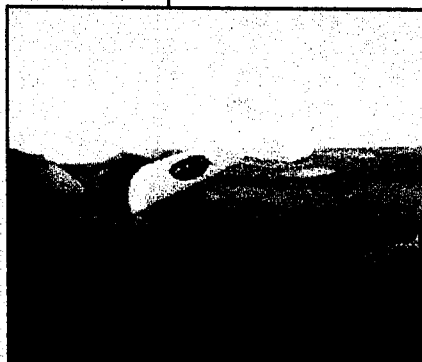
*Bridging the gap between orbital and surface platform data*



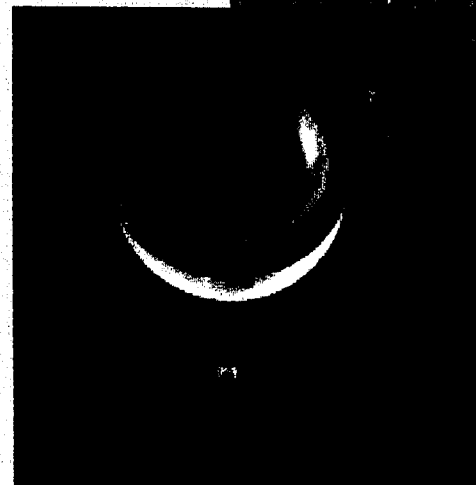
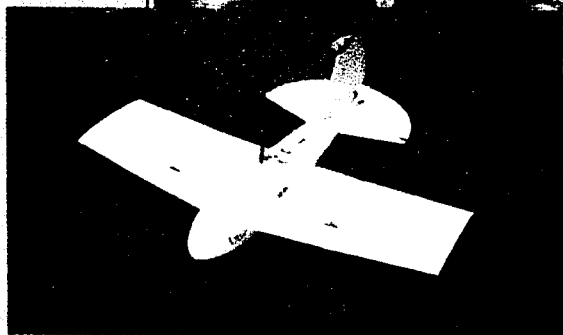
**Earth-based  
technology  
validation**



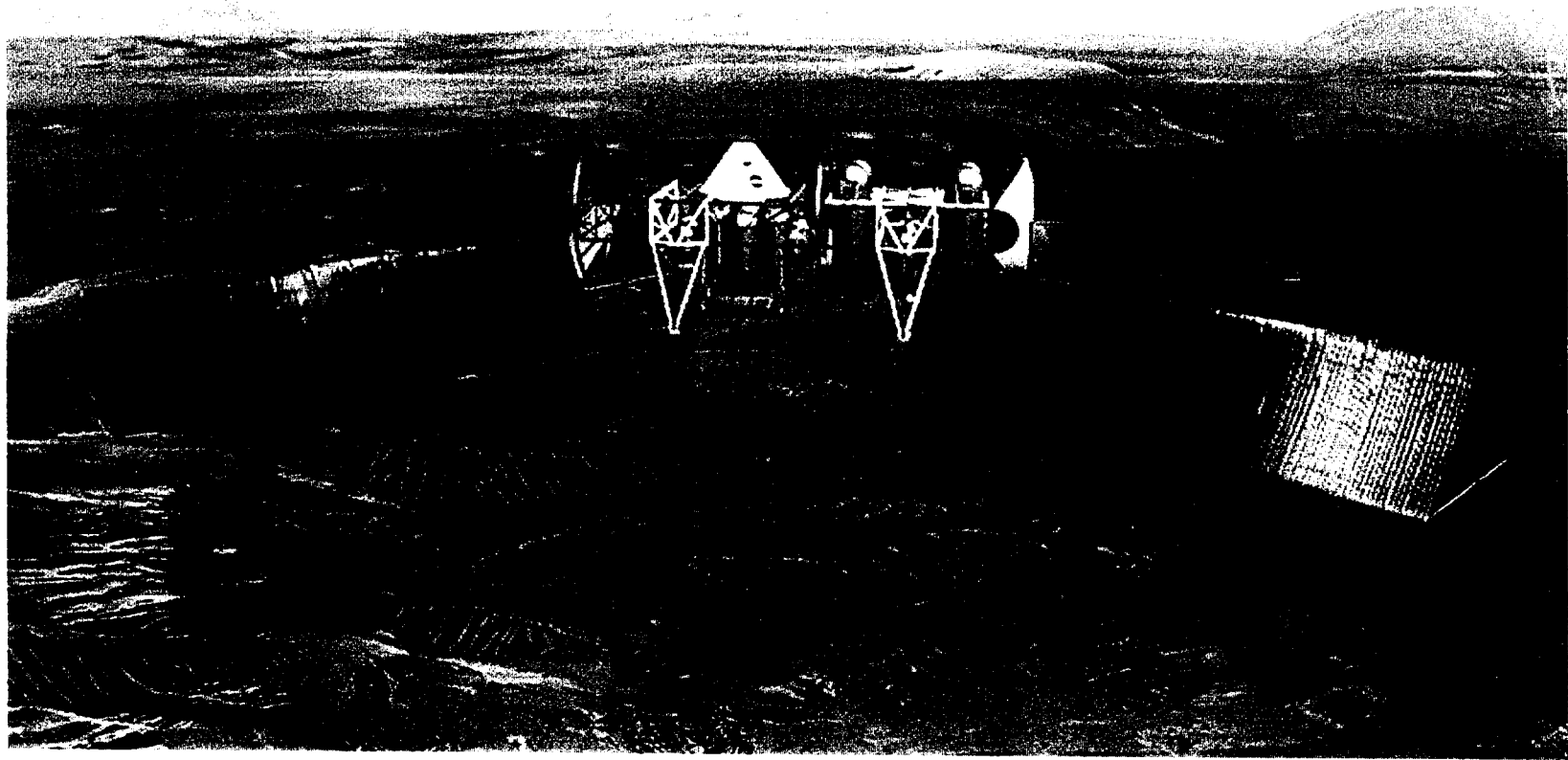
**Technology  
demonstrations  
at Mars**



**Scientific  
investigations  
at Mars**



# ***In-Situ* Resource Production Unit**



# Paving the Way for Future Exploration

